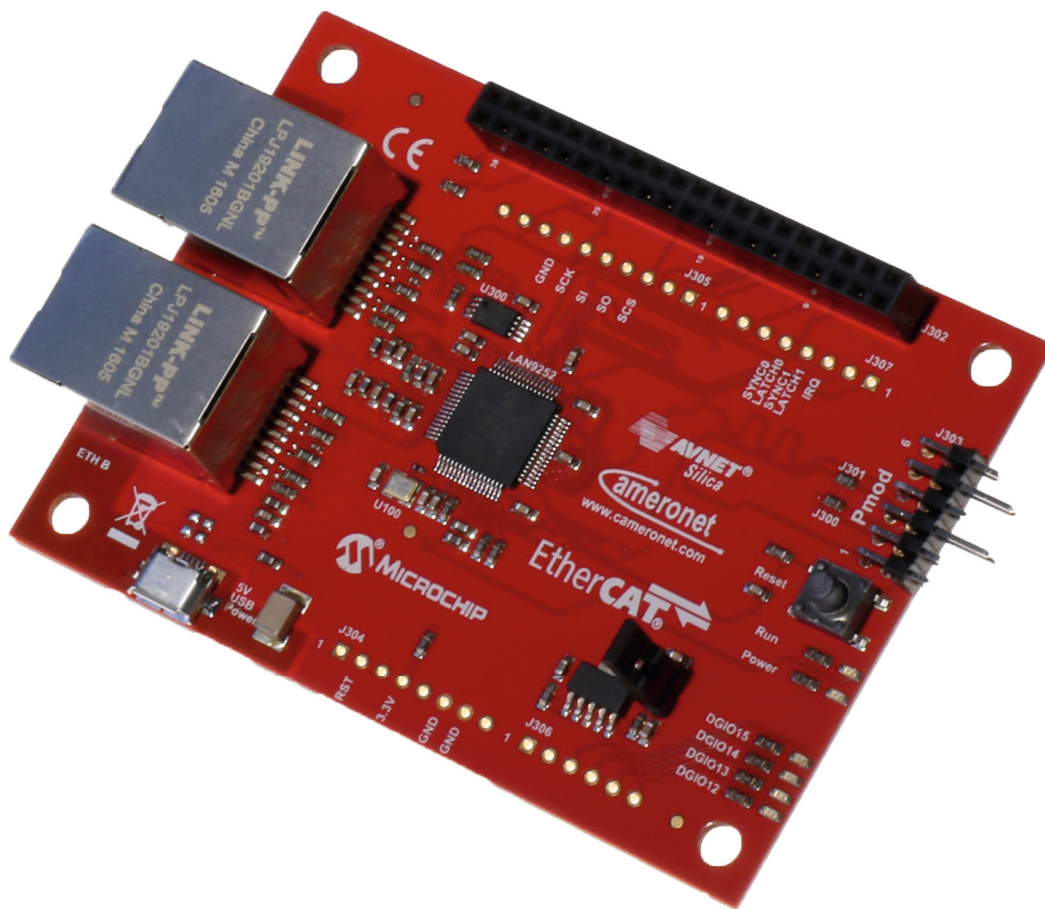


EtherCat Starter Kit

AVNET[®] SILICA

QUICK START GUIDE

THE PMOD-COM-ETHERCAT ETHERCAT[®] STARTER KIT FROM AVNET SILICA IS BASED ON THE MICROCHIP LAN9252 ETHERCAT SLAVE CONTROLLER.



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Overview

INTRODUCTION

The PMOD-COM-ETHERCAT EtherCAT® Starter Kit from Avnet Silica is based on the Microchip LAN9252 EtherCAT Slave controller. The easy to use EtherCAT Starter Kit has a Pmod™ and Arduino compatible interface, as well as a header with all I/Os of the LAN9252, which allows the direct connection to microcontroller starter kits from many suppliers for fast prototyping.

The LAN9252 EtherCAT slave controller has integrated 100base-TX PHYs with auto-MDIX, cable diagnostic and support for 100base-FX fiber as well. The flexible host interface can be configured as SPI, QSPI or 8/16bit parallel interface. The LAN9252 supports single supply and extended temperature range up to 105°C. Three operation modes are available:

- Digital I/O Mode: directly control 16 I/O signals without any MCU
- Microcontroller Mode: a microcontroller is connected via SPI, QSPI or parallel interface and runs the EtherCAT stack and application
- Expansion Mode: the third network port can be used to enable star or tree network configuration

TwinCAT 3 - extended Automation Technology Suite from Beckhoff Automation GmbH is used as EtherCAT master and configuration tool. Other EtherCAT masters and tools can be used as well.

This Quick Start Guide describes the basic steps how to use the PMOD-COM-ETHERCAT EtherCAT Starter Kit in Digital I/O Mode.

REFERENCES

See the following documents for further information about the PMOD-COM-ETHERCAT and LAN9252.

Visit <http://avnet-silica.com/ethercat> for the latest PMOD-COM-ETHERCAT documentation

- Quick Start Guide
- User's Guide
- ESI Device Description Files
- Application Example

Visit <http://www.microchip.com/wwwproducts/en/LAN9252> for the latest LAN9252 documentation

- LAN9252 datasheet
- AN1907 - Microchip LAN9252 migration from Beckhoff ET1100
- AN1911 - AN1911 Microchip LAN9252 power management
- AN1916 - AN1916 integrating Microchip's LAN9252 SDK with Beckhoff's EtherCAT SSC
- AN1920 - AN1920 Microchip LAN9252 EEPROM configuration and programming
- AN1995 - LAN9252 SOC porting guidelines

Visit <https://www.ethercat.org> for further information about EtherCAT technology, specification, FAQ and ETG membership.

EtherCAT Starter Kit

THIS CHAPTER DESCRIBES THE STEPS TO SETUP THE STARTER KIT AND SOFTWARE

SYSTEM SETUP

A basic EtherCAT system is built up with an EtherCAT master and the EtherCAT slave starter kit.

Required hardware and software:

- PMOD-COM-ETHERCAT starter kit
- USB cable with Micro B connector to supply power to the board (not included in the starter kit)
- Ethernet cable (not included in the starter kit)
- TwinCAT 3 (download from Beckhoff website)
- Device description file and application example (download from Avnet Silica website)

The PC runs TwinCAT, functions as the EtherCAT master and the PLC to run an application controlling the EtherCAT starter kit (EtherCAT slave). Multiple starter kits can be connected in a daisy chain.

CONNECT THE HARDWARE

Connect an Ethernet cable from the Ethernet Port ETH A (EtherCAT IN) of the EtherCAT starter kit to the Ethernet port of the PC, as shown in figure 1.

Connect a USB cable (A/Micro B) from the PC, USB hub or USB power supply to the EtherCAT starter kit micro USB connector to supply power to the board, as shown in figure 1.

After connecting the starter kit to the USB power, the Power LED and the DIGIO12 to DIGIO15 LEDs on the board are illuminated.

EtherCAT ports of the starter kit:

- ETH A: EtherCAT IN
- ETH B: EtherCAT OUT

Check the user guide for details about the hardware.

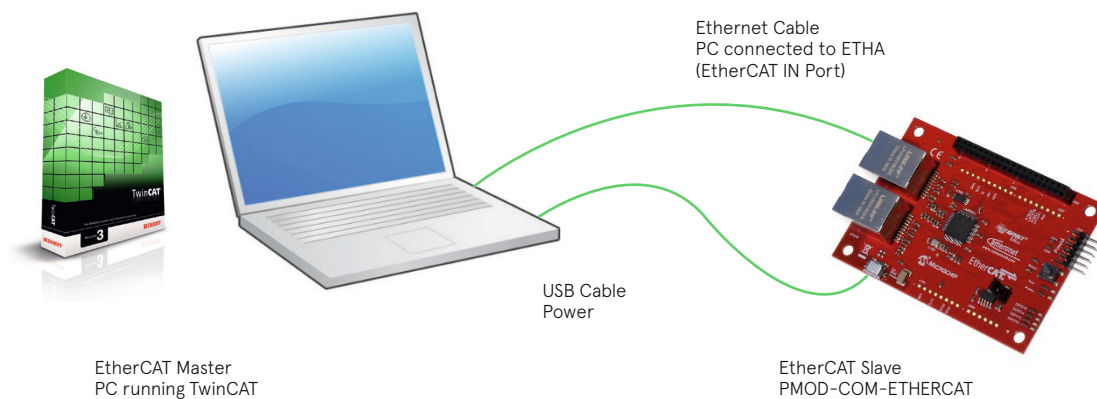


Figure 1 - System Setup

INSTALL THE SOFTWARE

Proceed the following steps and install all software and files.

Download and install TwinCAT 3

- Go to the Beckhoff website and download TwinCAT 3 XAE, version 3.1.4022.0 or later:
<http://beckhoff.com/english.asp?download/tc3-download-xae.htm>
- You have to register yourself and will get the download link by e-mail. Either register a guest or create an account.
- Unpack the downloaded file (TC31-Full Setup.3.1.4022.0.zip) and install the software by double-clicking on the executable.

Download and install device description file

- Go to the Avnet Silica website and download the device description file package (AVS-PMOD-COM-ETHERCAT_ESI.zip): <http://avnet-silica.com/ethercat>
- Unpack the archive and copy the file AVS-PMOD-COM-ETHERCAT_DIGIO_8IN_8OUT.xml to the TwinCAT 3 directory C:\TwinCAT\3.1\Config\Io\EtherCAT.

Download TwinCAT 3 example solution

- Go to the Avnet Silica website and download the TwinCAT example package (AVS-PMOD-COM-ETHERCAT-DIGIO.tnzip): <http://avnet-silica.com/ethercat>
- Save the file.

SETUP AND RUN THE DEMO

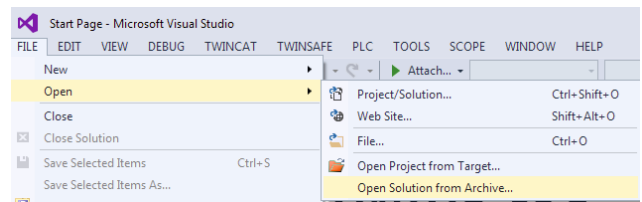
To setup the TwinCAT software and run the demo application, proceed according to the steps below.

Start TwinCAT

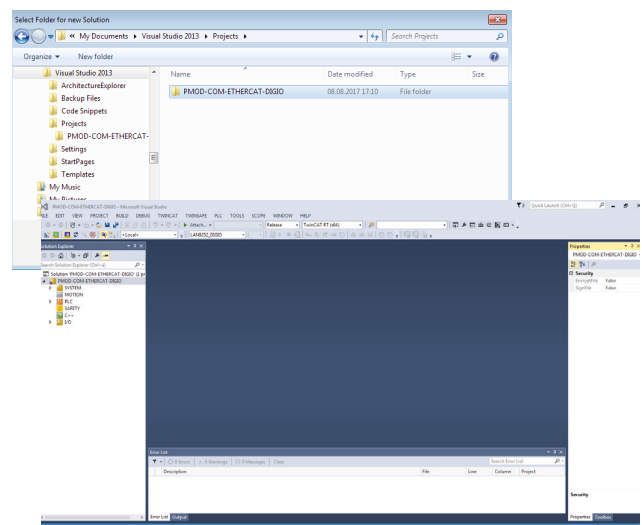
Windows Start Menu → All Programs → Beckhoff → TwinCAT3 → TwinCAT XAE (VS 2013)

Open demo solution in TwinCAT

- File → Open → Open Solution from archive
- Select the downloaded and saved file AVS-PMOD-COM-ETHERCAT-DIGIO.tnzip

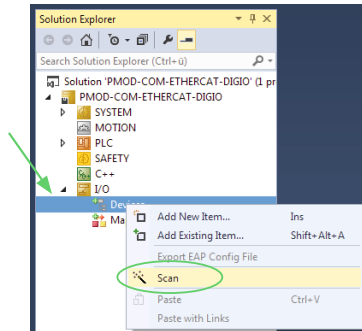


- A folder select window opens to select the project folder to be used. Select the folder of your choice, typically: My Documents\Visual Studio 2013\Projects\PMOD-COM-ETHERCAT-DIGIO
- The project window opens.

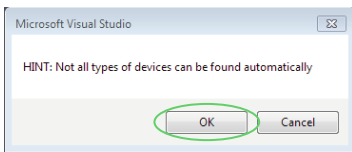


Scan for the EtherCAT starter kit

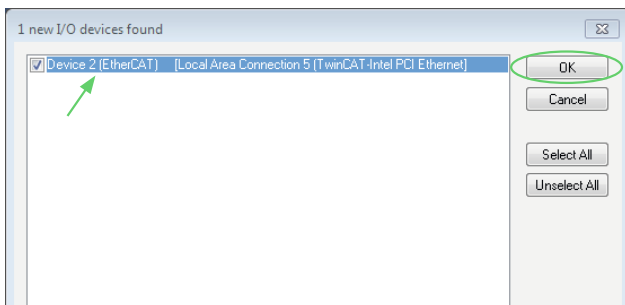
- Click on the arrow next to I/O in the solution explorer tree, then select "Devices". Right click and select "Scan" in the pop-up menu.



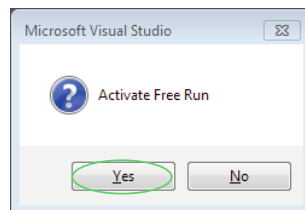
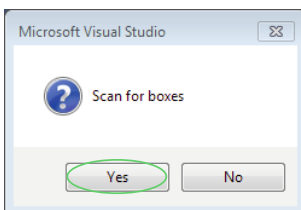
- Click "OK" in the "HINT" pop-up window.



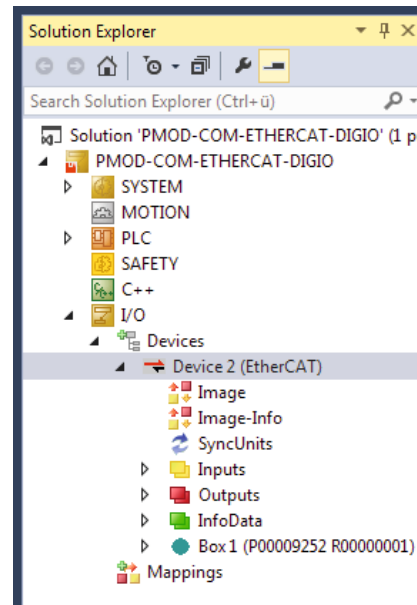
- In the I/O device window select the "Device 2 (EtherCAT)" and click "OK".



- Scan for boxes, click "Yes"
- Activate Free Run, click "Yes".

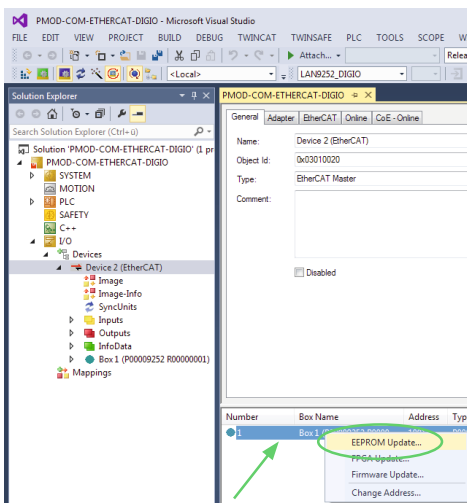


- The EtherCAT master (Device 2) and the EtherCAT slave (Box 1) appear in the tree.

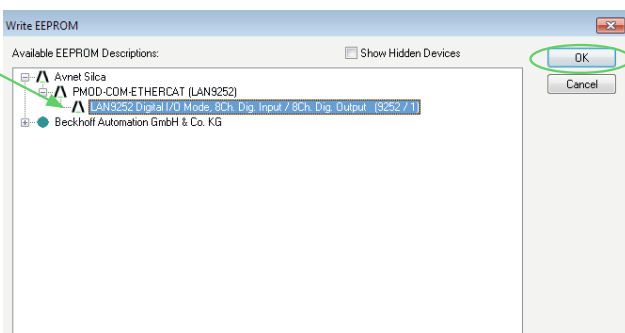


Program the EEPROM

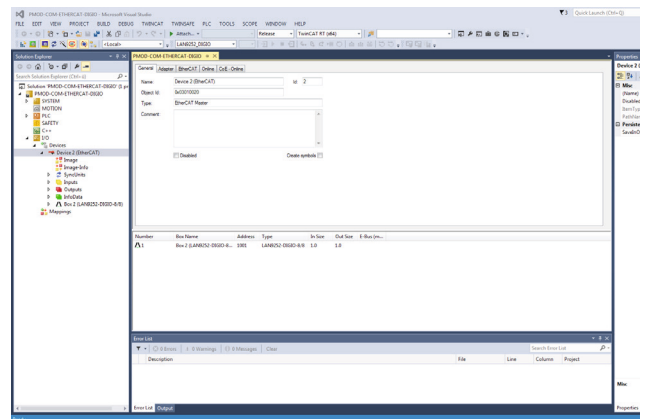
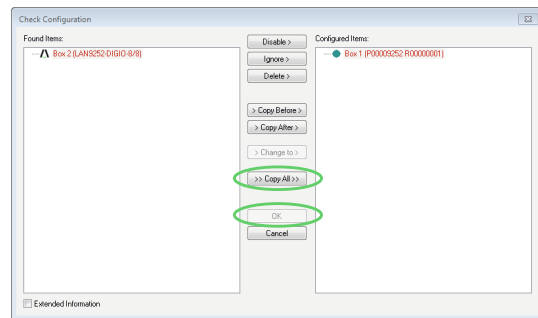
- This step only needs to be done the first time after unpacking the board, or if the EEPROM has been programmed with another configuration.
- Double click on "Device 2 (EtherCAT)". In the middle of the window the Box 1 is listed.
- Right click on Box 1 in the middle of the General Tab window and select "EEPROM Update".



- In the Write EEPROM window select the Digital I/O configuration listed under Avnet Silica and click "OK". The EEPROM will be programmed.
- LAN9252 Digital I/O Mode, 8Ch. Dig. Input / 8Ch. Dig. Output (9252 / 1)

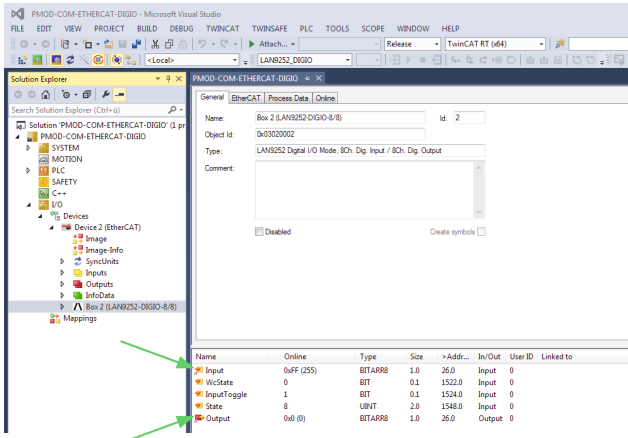


- Select "Device 2 (EtherCAT)" in the solution tree, right click and select "Scan". The Check Configuration window pops up.
- Click on ">> Copy All >>", then click "OK". The configuration is updated with "Box 2 (LAN9252-DIGIO-8/8)".

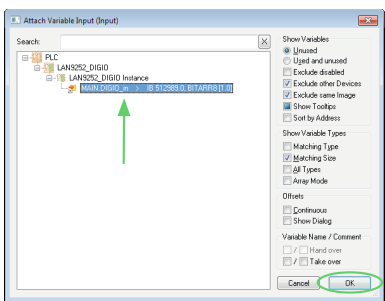


Mapping the I/O to the PLC example program

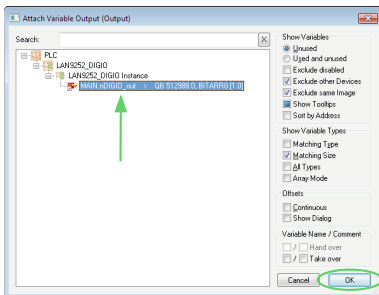
- Select "Box 2 (LAN9252-DIGIO-8/8)" in the solution explorer tree. In the General Tab the Inputs and Outputs are listed.



- Double click on the name "Input".
- In the Attach Variable Input window select "MAIN.DIGIO_in" and click "OK".

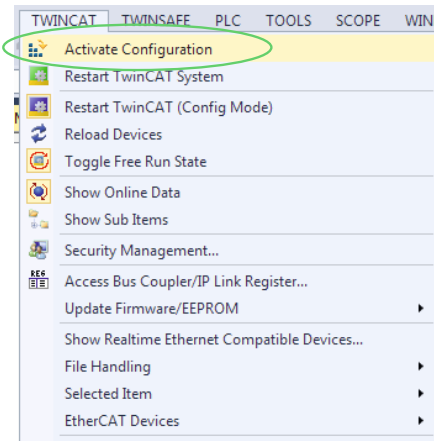


- Double click on the name "Output".
- In the Attach Variable Input window select "MAIN.DIGIO_out" and click "OK".

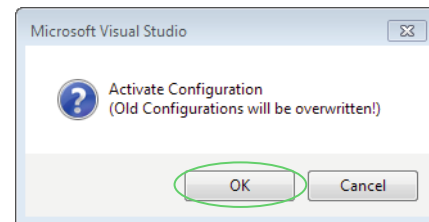


Run the demo

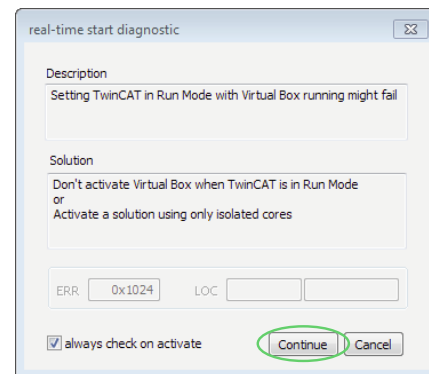
- In the menu "TWINCAT", click on "Activate Configuration"



- Activate Configuration (Old configurations will be overwritten), click "OK"

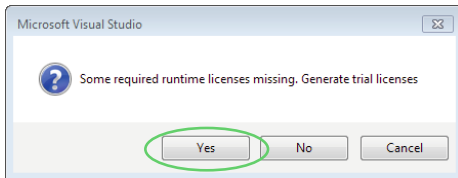


- Click "Continue" in the "real-time start diagnostic" pop-up window.

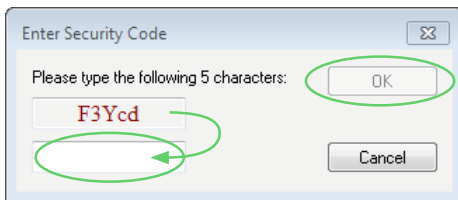


Runtime License

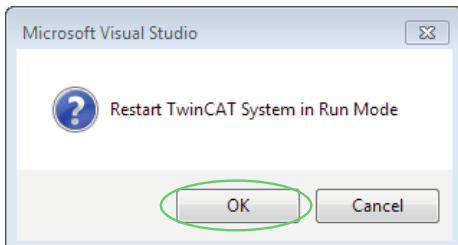
- If no valid license is found, a pop-up window to generate a Trial License will open. Click on "Yes".



- In the security code pop-up window, type in the displayed code and click "OK".



- Restart TwinCAT System in Run Mode, click "OK"



Now the PLC demo program starts and controls the LEDs on the starter kit.

Congratulations, you successfully set up a simple EtherCAT network and application.

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